|                   |   | _  |                          | 1                         |                      | r              |                                      |  |  |  |
|-------------------|---|--|--------------------------|---------------------------|----------------------|----------------|--------------------------------------|--|--|--|
|                   |   | SEE  | Cairo                    |                           | University           |                |                                      |  |  |  |
|                   | Susta   | ainable Energy E   | ngineering               | Ig Faculty of Engineering |                      | g              | 1908                                 |  |  |  |
|                   |   | Program  |                          | Credit                    | Hours System         |                | 2008   ם ם  <br>جامعة القاهرة        |  |  |  |
|                   |   |  | <b>Course Sp</b>         | ecifications              |                      |                |                                      |  |  |  |
| Program on        | ı which th  | is course is given:  | B. Sc. of Su             | stainable Energy          | y Engineering (      | (SEE)          |                                      |  |  |  |
| Department        | t offering  | the program:   | Credit Hou               | rs System, Facul          | ty of Engineeri      | ng, Cai        | ro University                        |  |  |  |
| Department        | t offering  | the course:  | Mechanical               | Power Engineer            | ring Dept - AC       | <u>C Cont</u>  | rol Lab                              |  |  |  |
| Academic L        | <u>evel:</u>  | · · · · · ·  | 400 Compu                | ilsory Course             | (Junior or Se        | nior-1         | or Senior-2)                         |  |  |  |
| Semester (b       | ased on f   | inal exam timing)  | 1 <sup>ar</sup> Semester | • V Fall 2023/20          | 024                  |                |                                      |  |  |  |
| A- Basic Iı       | oformati  | ion  |                          |                           |                      |                |                                      |  |  |  |
| 1. Title:         |   | Applied Co   | ntrol Techno             | ologies for Energ         | y Systems            | Code           | e: MEPS 305                          |  |  |  |
| 2. Credits: 3     | 3 (2+1+1)   | Lectures=2 hou   | rs/wk Tu                 | torial=1 hr/wk            | Practical=1 h        | nr/wk          | Fotal CHs =3                         |  |  |  |
| Prerequisite      | s: MTHN   | 003, MEPN224   |                          |                           |                      |                |                                      |  |  |  |
| <b>B- Profess</b> | ional In  | formation  |                          |                           |                      |                |                                      |  |  |  |
|                   | Part-1 (  | Control Theory):   | حسب خطةالدر اس           | بالتبادل مع الجزع-2       | لجز عبعد الجز ع-2 أو | بس هذا ال      | ملاحظة:بمكن تدر                      |  |  |  |
|                   | Power s   | vstems: Basic prin   | nciples, syste           | em, modeling, o           | lesign, simulati     | ion. an        | alvsis. Control                      |  |  |  |
|                   | systems-  | transfer function-   | closed loop-             | reduction, respon         | se, classical me     | thods-         | transitional and                     |  |  |  |
|                   | steady st   | ate- stability- Bode   | diagram- frec            | juency response.          | ,                    |                |                                      |  |  |  |
|                   | <b>Overall</b>  | Aims of Part-1:  | C .                      |                           |                      |                |                                      |  |  |  |
|                   | Part-1 is designed to show basic concepts & essentials of classical automatic control theory as it  |  |                          |                           |                      |                |                                      |  |  |  |
|                   | is applied on mech. power energy systems & heat and mass transfer processes. This part  |  |                          |                           |                      |                |                                      |  |  |  |
|                   | includes large numbers of practical examples and problems on various types of control systems   |  |                          |                           |                      |                |                                      |  |  |  |
|                   | to enhance student's professional skills in the field of modeling & analyzing real automatic  |  |                          |                           |                      |                |                                      |  |  |  |
|                   | control of energy systems. Overall aims are to define automatic control theory and associated   |  |                          |                           |                      |                |                                      |  |  |  |
|                   | terminology- introduce and study various types of control of energy Systems- mechanical   |  |                          |                           |                      |                |                                      |  |  |  |
|                   | components, pneumatic, hydraulic, electric systems-Mathematical Modeling of control   |  |                          |                           |                      |                |                                      |  |  |  |
|                   | systems-Laplace and inverse Laplace transformations-Element and System Transfer functions -   |  |                          |                           |                      |                |                                      |  |  |  |
|                   | Close an  | Close and open loop systems -Instantaneous system response-system stability & equilibrium    |                          |                           |                      |                |                                      |  |  |  |
|                   | tests -Design of control systems -Bode Plots & Analysis of Frequency Response of Control  |  |                          |                           |                      |                |                                      |  |  |  |
|                   | systems-Practical applications of automatic control theory in different mechanical power and  |  |                          |                           |                      |                |                                      |  |  |  |
|                   | heat transfer and mass transfer processes and equipments.   |  |                          |                           |                      |                |                                      |  |  |  |
|                   | Part-2 (Hydraulic Control Circuits):  |  |                          |                           |                      |                |                                      |  |  |  |
| 1. Course         | Applications of Automatic control: Hydraulic control, Hydraulic pumps and motors-   |  |                          |                           |                      |                |                                      |  |  |  |
| description:      | Controlvalves-Transmission components of power control- Pressure and flow valves- Applied   |  |                          |                           |                      |                |                                      |  |  |  |
|                   | ON/OFF Circuits.  |  |                          |                           |                      |                |                                      |  |  |  |
|                   | <b>Uverall AIMS OF Part-2:</b><br>Part-2 is designed to show the basic concepts and essentials of Hydraulic Circuits as it is applied   |  |                          |                           |                      |                |                                      |  |  |  |
|                   | ran-2 is designed to snow the basic concepts and essentials of Hydraulic Circuits as it is applied<br>in automatic control of mechanical power and energy systems. This part uses the Virtual Lab |  |                          |                           |                      |                |                                      |  |  |  |
|                   | m automatic control of mechanical power and energy systems. This part uses the virtual Lab<br>method by a practical on-line interactive PC program. This control Virtual Lab is an E-self-        |  |                          |                           |                      |                |                                      |  |  |  |
|                   | learning type software. The software includes large number of examples for hydraulic parts and  |  |                          |                           |                      |                |                                      |  |  |  |
|                   | circuits, 3-D animations, e-learning labs, quizzes, etc. This   |  |                          |                           |                      |                | s Virtual Lab program along with the |  |  |  |
|                   | course no   | otes & sheets provi  | example for mode         | ern self-learning         | educat               | ion techniques |                                      |  |  |  |
|                   | for studying and analyzing various aspects related to applications of ON/OFF Hydraulic  |  |                          |                           |                      |                |                                      |  |  |  |
|                   | Circuits in automatic control of mechanical power and energy systems. Part-2 overall aims are   |  |                          |                           |                      |                |                                      |  |  |  |
|                   | to introduce and study basic definitions of Hydrostatics (i.e., Pressure, work, transportation and  |  |                          |                           |                      |                |                                      |  |  |  |
|                   | magnification of force and moment). Hydraulic Power Transportation-Basic Components of  |  |                          |                           |                      |                |                                      |  |  |  |
|                   | Hydraulic Systems-Types of Positive Displacement Pumps(Gear, Vane, and piston pumps)-   |  |                          |                           |                      |                |                                      |  |  |  |
|                   | Types of  | f Hydraulic Actuat   | ors (Cylinder            | rs, Engines, Sem          | i-rotating Engir     | nes)- Pr       | essure control                       |  |  |  |
|                   | Valves –  | Directional Contro   | l Valves- Flo            | w Control Valve           | s-Non-return Va      | alves–C        | onditioning of                       |  |  |  |
|                   | Hydraulic Oils (filters, Heat Exchangers, Tanks)- Oil Piping – Auxiliaries (Accumulators,   |  |                          |                           |                      |                |                                      |  |  |  |
|                   | Manifolds, Flow Meters, Pressure Gauges, Switches)-Hydraulic Symbols -Reading Hydraulic   |  |                          |                           |                      |                |                                      |  |  |  |
|                   | Schemati  | chematics- Applications for Basic Hydraulic Circuits (Direction & Speed Control, 2 cylinders |                          |                           |                      |                |                                      |  |  |  |

Control, Pumps Curves, Step-displacement diagram, Numbering of Hydraulic Elements).

|  | Part-1 LO's:  |                                 |                            |                           |  |  |  |  |
|--|---|---------------------------------|----------------------------|---------------------------|--|--|--|--|
|  | 1.Recognize and identify different types of automatic control systems and control loops. Also to  |                                 |                            |                           |  |  |  |  |
|  | understand basic concepts and definitions of classical control theory.  | is of classical control theory. |                            |                           |  |  |  |  |
|  | 2. Apply mathematical modeling analysis of control systems & use block diagram presentation.  |                                 |                            |                           |  |  |  |  |
|  | Also use Laplace transforms technique to solve the Transfer Function of Control System.<br>3.Find instantaneous time-response of control systems & examine its graphical presentation. Al |                                 |                            |                           |  |  |  |  |
| 2. Learning  |   |                                 |                            |                           |  |  |  |  |
| Outcomes of  | understand frequency response of control systems and investigate the Bode Diagram Plots   |                                 |                            |                           |  |  |  |  |
| Course   | Part-2 LO's.  |                                 |                            |                           |  |  |  |  |
| (LOs):   | 4. Recognize various applications of Virtual Lab Techniques to study control systems. Also apply  |                                 |                            |                           |  |  |  |  |
|  | educational Virtual Lab to understand basics & essentials of Hydraulic control systems.   |                                 |                            |                           |  |  |  |  |
|  | 5. Investigate various components, parts and accessories of Hydraulic Circuits. Also understand   |                                 |                            |                           |  |  |  |  |
|  | hydraulic symbols and schematics used for drawing hydraulic circuits.   |                                 |                            |                           |  |  |  |  |
|  | 6. Practice reading symbol-schematics of hydraulic circuits. Also perform function analysis to  |                                 |                            |                           |  |  |  |  |
|  | select proper parts for circuits with optimum performance   |                                 |                            |                           |  |  |  |  |
| 3-9 Conten   | ts of Part-1: بعد نهاية الجزء-2 أو بالتبادل مع الجزء-2 جسب خطة الد إسة المعانة (1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-  | الحزع                           | مکن تدریس                  | ملاحظة، ي                 |  |  |  |  |
| 5-a. Conten  | ي بندوني بين كافة وجاض ابتروتوارين الدن عالاول عنه الكرام ومسموم On داخل وقد الكارة بالدونية  | ظقوامة                          |                            |                           |  |  |  |  |
| م الأمل فقط  | <u>.</u> يتم تدريس محدد معاصرات وتعارين البر (الوق) Son-campus داخل معراصية بالبيرة .<br>برمن الترم (كان أسيم عمد اضر قريسكاثين جتر مم عد امتحان المرد ترم الأمريسية تصر على الجز         |                                 | <u>المارية مان المراني</u> | i ettia                   |  |  |  |  |
|  | ) من الكرم (فن المنبوع مصلصرة بالمنصل على من حق إمصان المنبية كرم الذي مسيطل على البير  | Total                           | Lectures                   | Tutorial/                 |  |  |  |  |
| <b>Topics of Pa</b>  | انظر ملف خطة الدراسة التفصيلية على موقع معمل التحكم +على جوجل كلاس رووم : <art-1< td=""><td>hrs</td><td>hours</td><td>Practical hr</td></art-1<>  | hrs                             | hours                      | Practical hr              |  |  |  |  |
| -Introduction  | to Basics, definitions & terminologies associated with automatic control  |                                 |                            |                           |  |  |  |  |
| theory.  |   |                                 |                            |                           |  |  |  |  |
| -Various type  | s of automatic control loops in mech. power & energy transfer systems.  |                                 |                            |                           |  |  |  |  |
| -Essential req   | uirements of accuracy, efficiency, safety, and stability of control systems   |                                 |                            |                           |  |  |  |  |
| -Concepts of   | mathematical modelling of various mechanical power systems and energy   |                                 |                            | Three wool                |  |  |  |  |
| transfer proce   | sses  |                                 | 2hrs/week                  | for                       |  |  |  |  |
| -The element   | & whole system transfer functions & Block diagram analysis method.  |                                 | IOr<br>7 weeks             | 7 weeks                   |  |  |  |  |
| -Laplace Tra   | nsform & inverse Laplace technique to solve the system's ordinary time-   | 28 hrs                          | / weeks                    | before                    |  |  |  |  |
| dependent dif  | referential equations.  |                                 | The Mid                    | The                       |  |  |  |  |
| -instantaneou  | s dynamic response of control system and its graphical presentation on an   |                                 | Term                       | Final                     |  |  |  |  |
| -Main definit  | ions and control characteristics of dynamic response of $1^{st}$ and $2^{nd}$ order   |                                 | Exam                       | Term                      |  |  |  |  |
| automatic con  | ntrol systems   |                                 | Linuin                     | Exam                      |  |  |  |  |
| - The analog   | y between various types of mechanical control systems and electric control  |                                 |                            |                           |  |  |  |  |
| systems. Bode  | e Plots & Analysis of Frequency Response of Control systems.  |                                 |                            |                           |  |  |  |  |
| –Practical app   | plications of automatic control theory in different mechanical power and heat   |                                 |                            |                           |  |  |  |  |
| and mass tran  | sfer equipments.  |                                 |                            |                           |  |  |  |  |
| 3-b. Conten  | ts of Part-2 (Note that this is a Self-Study Virtual Lab Course)  |                                 |                            |                           |  |  |  |  |
|  | لجزء-2 بعد نهاية الجزء-1 أوبالتبادل مع الجزء-1 أسبوعياً حسب خطةالدراسةالمعلنة للطَّلام  | تدريس ا                         | حظة: يمكن                  | ملا                       |  |  |  |  |
| ع 9 حتى أسبوع  | رات وتمارين الجزءالثاني داخل الكلية+بواسطة النت (حسب الإعلان بذلك) وذلك من الأسبو   | ں <mark>محاض</mark>             | ة: يتم تدريد               | ملاحظةهام                 |  |  |  |  |
| بزءالثاني)   | أسبوع محاضرة+سكشن حتى موعد إمتحان نهايةالترم الذى سيشمل كل من الجزء الأول +الم  | نرم (کل                         | د إمتحان الذ               | <b>י</b> 15               |  |  |  |  |
| <b>Topics of Pa</b>  | أنظر ملف خطة الدراسة التفصيلية على موقع معمل التحكم +على جوجل كلاس رووم :art-2  | Total                           | Lectures                   | Tutorial/<br>Prostical hr |  |  |  |  |
| -Introduction  | Basics and definitions of Hydrostatics(i.e. work Pressure   | 111.5                           | nours                      |                           |  |  |  |  |
| transportatio  | n and magnification of force and moment).   |                                 |                            |                           |  |  |  |  |
| -Hydrodyna   | mics (Continuity Bernoulli's can Energy types of fluid flow)  |                                 |                            |                           |  |  |  |  |
| -Methods of  | Power transportation  |                                 |                            |                           |  |  |  |  |
| -Rasic comp  | opents of Hydraulic Systems-Types of Positive Displacement Pumps  |                                 | Thre/wool                  | Three wools               |  |  |  |  |
| Gear Vane  |   | for                             | for                        |                           |  |  |  |  |
| Cocal, Valle,  |   | 7 weeks                         | 7 weeks                    |                           |  |  |  |  |
| Valves Co  | 28 hrs  | before                          | before                     |                           |  |  |  |  |
| Varves - Col   | 20 1118   | The                             | The                        |                           |  |  |  |  |
| r ipilig-Auxi<br>Switches)                                       |   | Final                           | Final                      |                           |  |  |  |  |
| Undromline S   |   | 1 erm<br>Exam                   | 1 erm<br>Exam              |                           |  |  |  |  |
| (Direction C   |   | LAum                            | LAUIII                     |                           |  |  |  |  |
| diaplacements  |   |                                 |                            |                           |  |  |  |  |
| Dractical applications of automatic control Hydraulic Elements). |   |                                 |                            |                           |  |  |  |  |
| -Practical ap  | Practical applications of automatic control Hydraulic systems/systems in different  |                                 |                            |                           |  |  |  |  |
| mechanical p   | bower and neat and mass transfer equipments.  |                                 |                            |                           |  |  |  |  |

| 4. Teaching and Learning Methods   |   |                          |                       |             |                 |                |                   |                  |            |  |  |
|--|---|--------------------------|-----------------------|-------------|-----------------|----------------|-------------------|------------------|------------|--|--|
| Lecture  | Practical/  | Seminar/                 | Class                 | Case        | Ducienta        | Laboratory     | <b>E-learning</b> | Assignments      | Other:     |  |  |
| S  | Training  | Workshop                 | Activity              | Study       | Projects        | Laboratory     | Part-2            | /Homework        | Submitting |  |  |
| (√)  | (√)   | ()                       | $(\sqrt{)}$           | $(\sqrt{)}$ | ()              | ()             | ()                | (√)              | reports    |  |  |
| 5. Stud  | 5. Student Assessment Methods   |                          |                       |             |                 |                |                   |                  |            |  |  |
| As   | sessment S  | Schedule <mark>fo</mark> | <mark>r Part-1</mark> |             |                 |                |                   |                  | Week       |  |  |
| -Assess  | ment 1; Par   | rt-1 Sheet-1             | – Introduc            | ction to c  | control the     | eory           |                   |                  | Week #1    |  |  |
| -Assessment 2; Part-1 Sheet-2 – Mathematical modeling  |   |                          |                       |             |                 |                |                   | Week #2          |            |  |  |
| -Assessment 3; Part-1 Sheet-3 –Block Diagram   |   |                          |                       |             |                 |                |                   | Week #3          |            |  |  |
| -Assessment 4; Part-1 Sheet-4 – Laplace Transformations  |   |                          |                       |             |                 |                |                   | Week #4          |            |  |  |
| -Assessment 5; Part-1 Sheet-5 – System Transfer Function   |   |                          |                       |             |                 |                |                   | Week #5          |            |  |  |
| -Assess  | ment 6; Par   | rt-1 Sheet-6             | – System              | Analysi     | is & Dyna       | mic Response   | e                 |                  | Week #6    |  |  |
| -Assess  | ment 7; Par   | rt-1 Sheet-7             | – Genera              | l Problei   | ms on Par       | t-1            |                   |                  | Week #7    |  |  |
| As   | sessment S  | chedule <mark>fo</mark>  | r Part-2              |             |                 |                |                   |                  | Week       |  |  |
| -Assess  | ment 1; Par   | rt-2 Sheet-1             | Fluid Pov             | ver Phys    | sics            |                |                   |                  | Week #9    |  |  |
| -Assess  | ment 2; Par   | rt-2 Sheet-2             | – Pumps               | & Part-2    | 2 Sheet-3       | Actuators      | <u></u>           |                  | Week # 10  |  |  |
| -Assess  | ment 3; Par   | rt-2 Sheet-4             | -Pressure             | Control     | Valves&         | Part-2 Sheet-  | 5 Directional     | I Control Valves | Week # 11  |  |  |
| -Assess  | ment 4; Par   | rt-2 Sheet-6             | Flow Cor              | ntrol Val   | ves & Pa        | rt-2 Sheet-7 F | fluid Conditio    | oning            | Week # 12  |  |  |
| -Assessment 5; Part-2 Sheet-8 Check Valves & Part-2 Sheet-9 Accessory Components   |   |                          |                       |             |                 |                |                   | Week # 13        |            |  |  |
| -Assessment 6; Part-2 Sheet-10 Fluid Conductors & Part-2 Sheet-11Understanding Schematics  |   |                          |                       |             |                 |                | Week # 14         |                  |            |  |  |
| -Assess  | sment /;Part-   | -2 Sneet-12              | Basic system          | m Desigr    | a & Part-2 S    | sneet-13 Kevie | ew General R      | eport for Part-2 | week #15   |  |  |
| •  | Weighting   | of Assessn               | nents                 |             | . [             |                |                   |                  |            |  |  |
| -Mid-T   | erm Exam (  | (written &               | Open Bool             | k) on Pa    | rt-1 <b>20%</b> | 2              |                   |                  |            |  |  |
| -All in-   | term works  | , sheets and             | l reports             |             | 40 9            | 70             |                   |                  |            |  |  |
| -Final-t   | erm formal  | written Ex               | amination             | (written    | & 40 9          | % (Open Boo    | ok Exam Type      | <mark>e)</mark>  |            |  |  |
| Open B   | look) on bo   | th Part-1 &              | Part-2                |             |                 | ( - F          |                   | - /              |            |  |  |
| -Projec  | -Project  |                          |                       |             |                 |                |                   |                  |            |  |  |
| -Class [   | Fest  |                          |                       |             |                 |                |                   |                  |            |  |  |
| -Presen  | tation  |                          |                       |             |                 |                |                   |                  |            |  |  |
| -Total   |   |                          |                       |             | 100             | 100%           |                   |                  |            |  |  |
| <ul> <li>6-a. List of References for Part-1:</li> <li>1- Several Class Notes, Self-Study Files, Reports and Materials prepared by Course Instructor.</li> <li>2- Katsuhiko Ogata, "Modern Control Engineering", Prentice Hall &amp; PEARSON, 2010.</li> <li>3-"Instrumentation and Control- Process Control Fundamentals", <u>www.pacontrol.com</u><br/>acc-vlab.cu.edu.eg معمل التحكم وعمر علي موقع معمل التحكم acc-vlab.cu.edu.eg</li> </ul>   |   |                          |                       |             |                 |                |                   |                  |            |  |  |
| 6-b. List of References for Part-2(Note that this is a Self-Study Virtual Lab Course):<br>1- Several Class Notes, Reports, and Self-study Materials prepared by Course Instructor.<br>2- E-Learning Software and Virtual Lab program by "Interactive Industrial Training, Inc.",<br><i>fluidpowerzone.com, a Newport vertical community 1987 north 1120 west Provo, UT 84604</i><br>acc-vlab.cu.edu.eg ملاحظة: يوجدعدد كبير من المادة العلمية والأفلام والمراجع للمقرر على جوجل كلاس رووم و على موقع معمل التحكم |   |                          |                       |             |                 |                |                   |                  |            |  |  |
| 7. Facilities Required for Teaching and Learning: Data Show and Laptop Computer  |   |                          |                       |             |                 |                |                   |                  |            |  |  |
| Course   | Coordina  | tor: A                   | ssociate l            | rofesso     | or Dr. Mo       | nsen S. Solin  | nan               |                  |            |  |  |
| SEE Pı<br>Coordi   | SEE ProgramProfessor Dr. Mohamed Ahmed Ali Yehia &Coordinators:Assistance Professor Dr. Ahmed Mahmoud Abouzid |                          |                       |             |                 |                |                   |                  |            |  |  |